Errata

In Section 5.3, "For each move, we optimize joint motor target velocities over a planning horizon of 1.5 seconds (C-PBP offline) or 0.5-2.0 seconds (CMA-ES)." should be "For each move, we optimize joint motor target velocities over a planning horizon of 1.5 seconds (C-PBP offline) or 0.5-1.5 seconds (CMA-ES)."

The caption of Fig. 2-(b), should be "The neighboring hold set of the left hand is the union of the holds that are inside the shaded area and the ones that are connected by dashed lines to the hold closest to the left hand, shown by red dot.", and in Section IV-B, "The holds connected by dashed-lines to the hold attached to the moving limb." should be "The holds con-

nected by dashed lines to the hold closest to the moving limb."