Errata

Publication I

In equation (4), the exponent of γ should be $d-1$, i.e. γ^{d-1}.
The constraints in (6) should be: $\sum_{h \in H_{d_1}} x_h = C_h$ and $0 \leq x_h \leq 1, \forall h \in H_{d_1}$.

Publication III

In equation (1), the exponent of γ should be $n-1$, i.e. γ^{n-1}.
In Section III.B, second column: $u^* = \sum_{t \in \mathbf{h}_i} \eta_i^{(t)}$.
For a complete computation of the state-action-value, the algorithm presented in Table I should be applied for all actions u.

Publication V

In equation (1) $s_m(t-1)$ should be instead of $s_m(t)$.